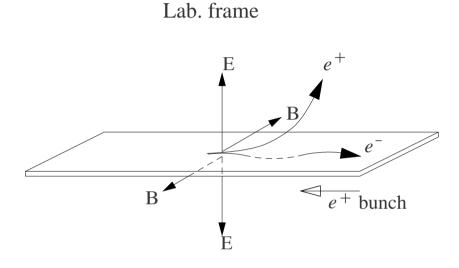
Beamprofile Monitor R&D based on 3D Sensor

Collaboration of Brunnel, Hawaii, KEK, Stanford, Tohoku

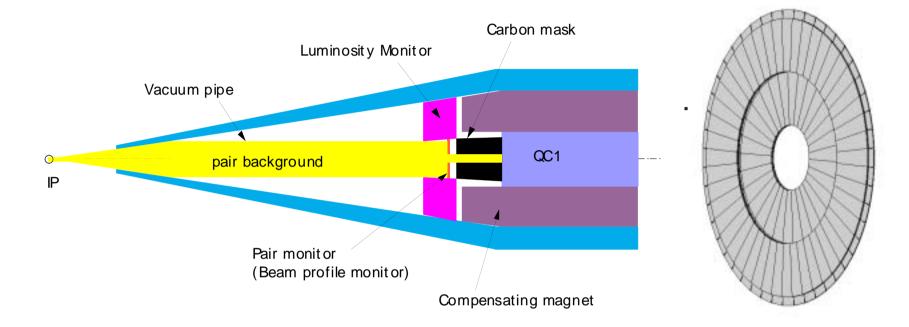
Presented by: Hitoshi Yamamoto (Tohoku University)

ECFA LC Workshop, Montpellier, Nov. 13, 2003.

Kinematic Configuration of Pair 'Background'

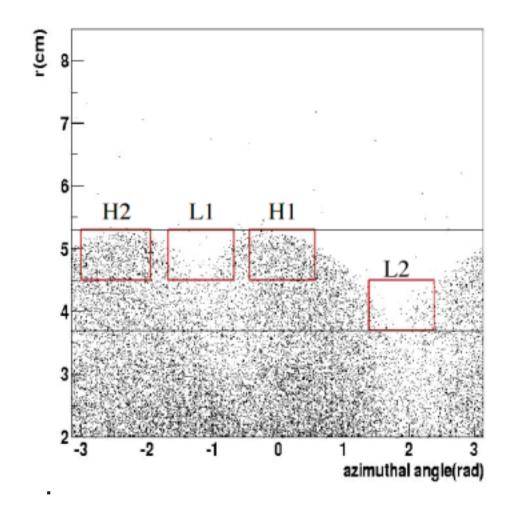


- For an incoming e^+ bunch,
 - e^- oscillates around the beam plane.
 - e^+ acquires a large p_t kick (vertical).
- Round beam \rightarrow no ϕ dependence, ϕ dependence $\rightarrow \sigma_y/\sigma_x$ ratio.
- Bunch identification desirable (at least roughly: $\sigma_t < 25ns$, train = 270 ns)
- High rate expected (30hits/train/mm²)



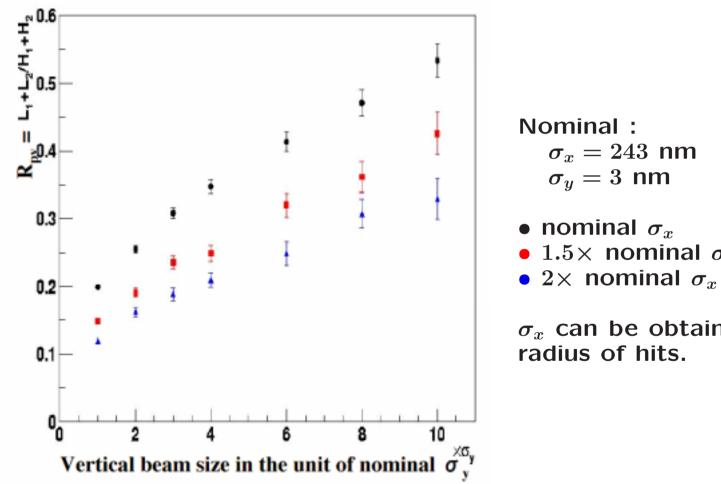
Outer radius \sim 8cm. One on each side of IP. Trapisoidal sensors desirable.

Pair hit distribution on the beam profile monitor



$$R\equivrac{L_1+L_2}{H_1+H_2}$$

Extraction of σ_y

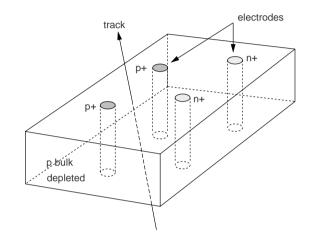


 $\sigma_x = 243$ nm $\sigma_y = 3 \,\,\mathrm{nm}$

• nominal σ_x • 1.5× nominal σ_x

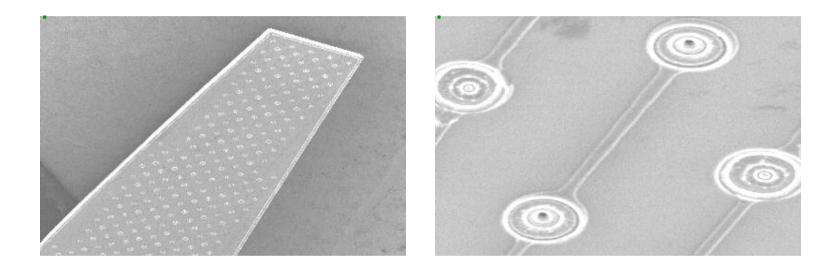
 σ_x can be obtained by max radius of hits.

3D pixel sensor



- 1. Fast. Charge collection time 10ns: \sim 10 times faster than conventional pixel sensor.
- 2. Rad-tolerant. Depletion voltage $\sim 5V \rightarrow < 50$ even after heavy dose (~ 10 MRad).
- 3. Complicated shapes possible (e.g. trapisoid).
- 4. Can be active all the way to the edge.

Fabrication of 3D pixel sensor



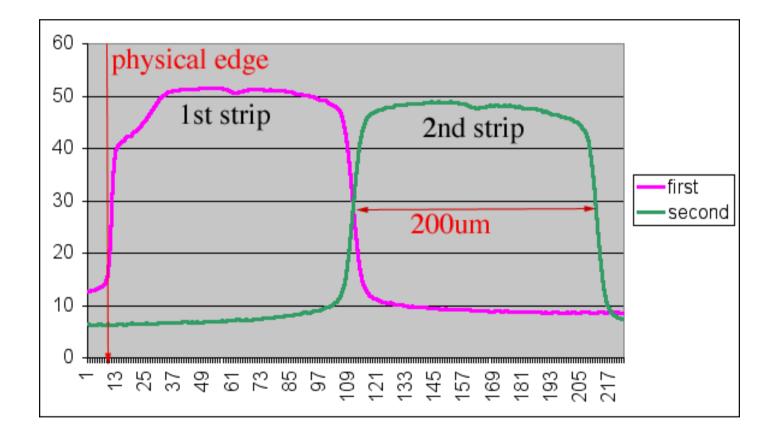
- 1. Fabricated by S. Parker et. al., at CIS, Stanford).
- 2. Trapezoidal shape possible for disk or cone. (180 μ m thick, 200 μ m readout pitch, 3mm long)
- 3. Fabrication completed and being tested at LBL and Tohoku.

X-Ray Test (rectangular version)

Goal: establish dead region at electrodes and edges

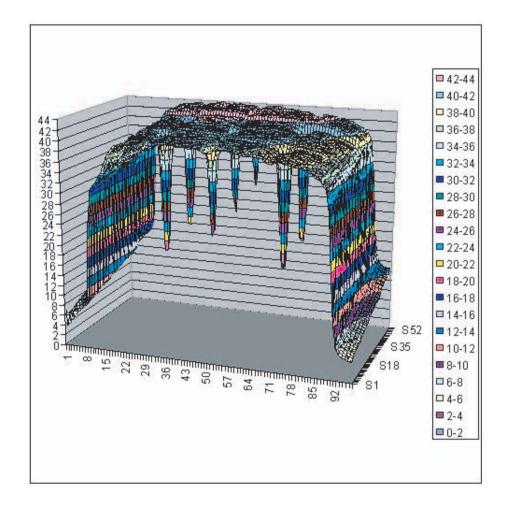
- 180 μ m thick, 200 μ m readout pitch
- Connected as strips for testing
- ALS (Advanced Light Source) at LBL
- 12 keV synchrotron X-rays (penetrates Aluminum metal layers)
- Focused to ${\sim}2\mu m$ spot size by elipsoisal X-ray mirrors
- Meausre the currents out of strips directly

Strip currents on 1st and 2nd strips



Dead region near edge $2\pm 2\mu$ m

Dead region near electrodes



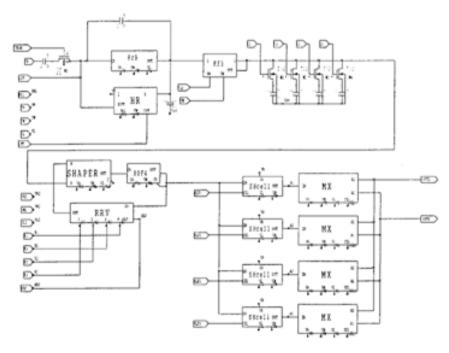
Current on any strip vs X-ray position (unit: 2μ m)

Pixel Readout Chip Prototype.

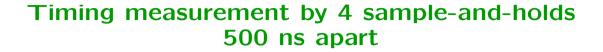
- 1. Cuicuit design by KEK and Tohoku.
- 2. SPICE Simulation study by Tohoku.
- 3. VLSI layout by a company in Hiroshima.
- 4. Submitted to VDEC (Rohm 0.35μ m).
- 5. Delivered on Jan 20, 2003.
- 6. Tested at Tohoku.

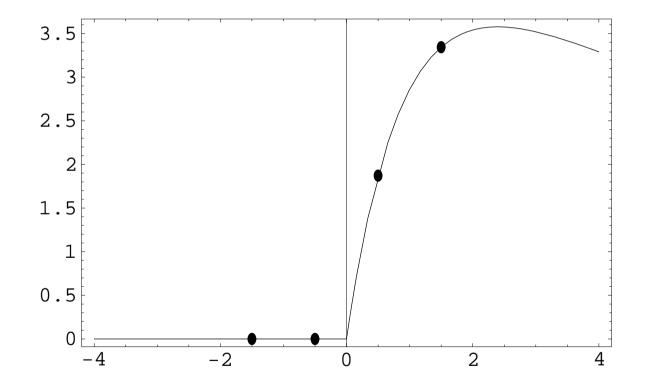
Readout electronics

Block diagram of the circuit



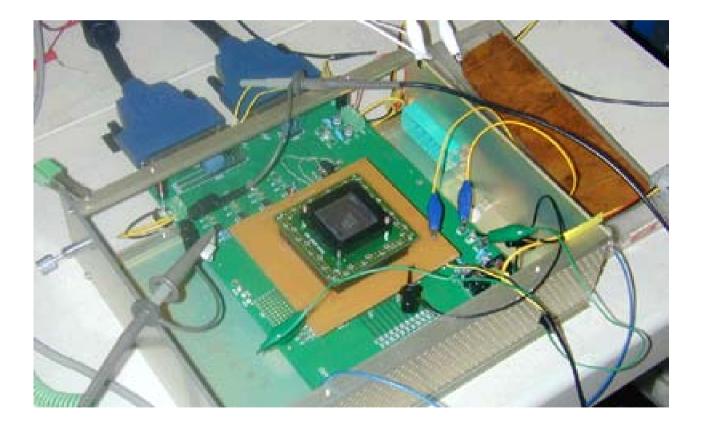
- 32ch per chip (prototype)
- Preamp → RC filter
 → Voltage amp. shaper
 → Sample and Hold
- 4 samplings →
 time and pulseheight
- Serial output of 4 vals/ch. as a step function.
- All functions verified.



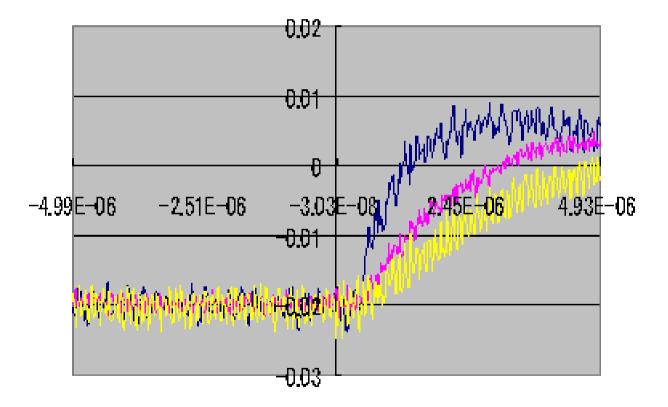


Fit the parametrized function \rightarrow time and pulse height.

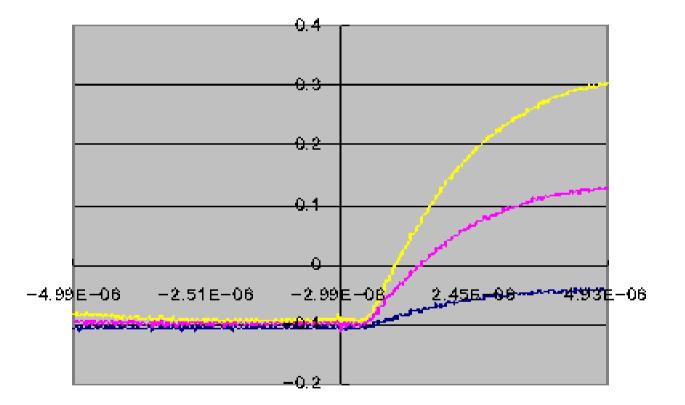
Readout Chip Test w/ Test Pulses



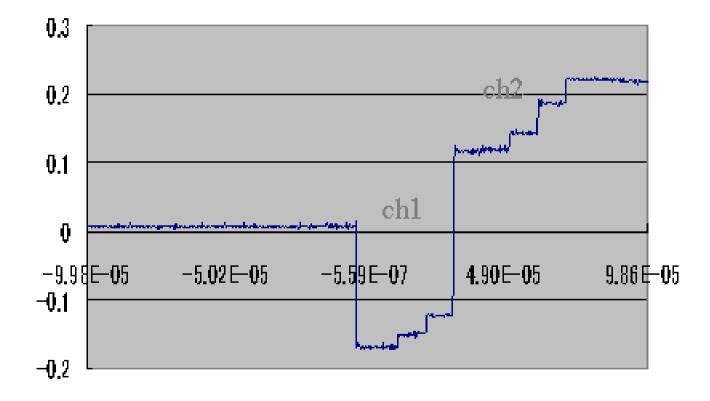
RC filter output (time contant varied)



Voltage amplifier output (gain varied)

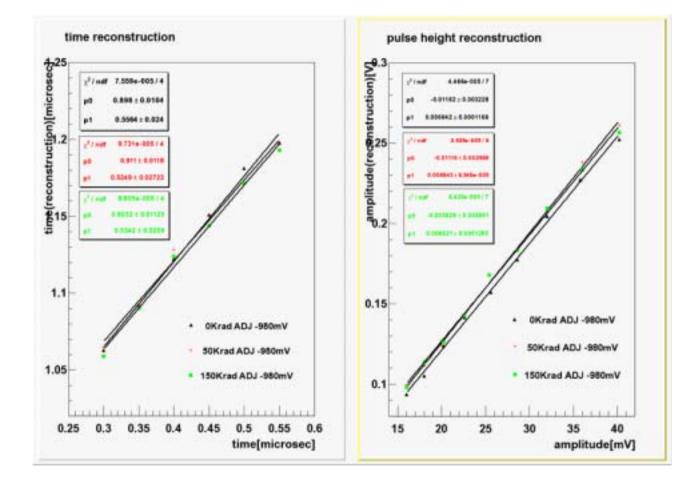


Serial readout output



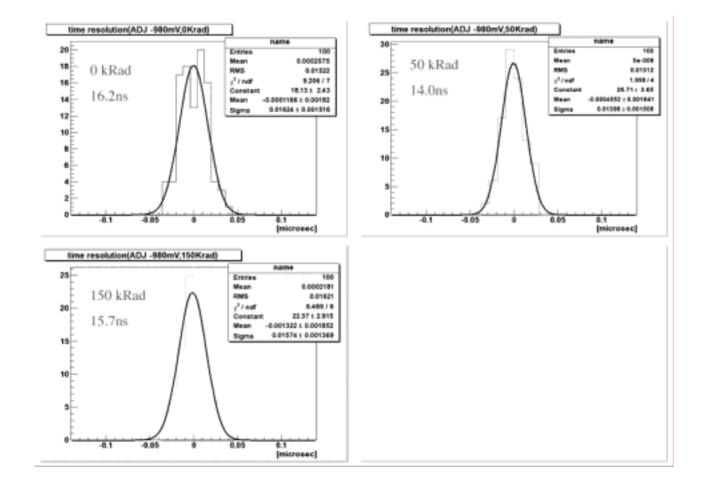
Radiation test (Co60)

2 MRad/yr expected close to the beam. Just started : upto 150 kRad now - test is on-going.



Radiation test (Co60)

No degradation up to 150 kRad ($\sigma_t \sim 16$ ns)



Next Steps

Sensor

- 1. Complete the test of the trapezoidal 3D sensor:
 - (a) I-V C-V curves.
 - (b) IR laser tests.
 - (c) Edge effects.
- 2. Connect an amplifier (candidate is the Viking chip) to the 3D sensor \rightarrow IR laser tests.

Readout chip

- 1. Complete the radiation test of the readout chip.
- 2. Design modifications and resubmission (if needed).
- 3. Solve size issue. (it should fit in 0.01 mm² and radhard to \sim 10 MRad)
- 4. Noise hits?